

RUTGERS Asphalt Paving Conference March 24-25, 2014 PAVE IR UPDATE

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MOBA PAVE-IR









Pilot Projects



System Demonstrations



University Research





PAVE-IR Update



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1998

Topics

The Problem

1995-1996

- **1999**
- **2000**
- **2001-2006**
- Washington DOT study 64 Projects



The Problem

 Localized "spots" of coarse surface texture
 Premature failure due to fatigue cracking, raveling, and moisture damage

Increased roughness







The Problem

Cooling of mix during transport is not remixed during the laydown process. Paver Set-up Results in erratic mat temperatures that are not apparent to the laydown crew.







Data Collected

- Haul distance and time
- Weather conditions
- Equipment
 - Type of truck
 - MTV/MTD
 - Paver
 - Roller
- Nuclear density data

- Temperature data
 - Infrared camera

thermometer

- Probes
- Hand held infrared
- Plant information
 - Temperature of mix
 - Loading operations
 - Mat Placement



1998 Conclusions

- None of the 4 projects experienced significant aggregate segregation.
- All 4 projects experienced significant temperature differentials.
- Concentrated areas of significantly cooler HMA generally resulted in lower than desirable compaction of those areas.



1998 Conclusions (cont.)

- Concentrated areas of cooler HMA commonly occur during construction (based on this study and others).
- Good rolling practices can partially offset temperature differential related compaction problems.
- MTVs not specifically examined.
- Temperature differentials are easily identified by infrared imaging.



End Dump/No MTV



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1999 Study Objectives

Investigate the effectiveness of different MTVs and remixing devices/methods Investigate other possible mitigation techniques Reexamine criteria for when and where to use MTV's 64 Projects Studies



End Dump/ MTV



SR 12



Effects on Pavement

- Same as insufficient compaction
 - Increased raveling and moisture damage
 - Reduced fatigue life
 - Increased roughness
- One percent increase in air voids results in a minimum of 10% reduction in pavement life (a rule of thumb)
- 25° F Differential=1 to 2% more air voids











Courtesy of PTI and Ron Collins



A number of State DOTs have developed and implemented specifications to address this issue.

WSDOT's current specification

2001-2006

- Cyclic density areas are defined as less than 89.0 percent of maximum density.
- If four or more low cyclic density areas are identified in a lot, a price adjustment will be assessed for that lot (a lot is 400 tons).
- The price adjustment will be calculated as 15% of the unit bid price of HMA represented by that lot.
- This assessment starts with examining the mat for temperature differences of 25°F or greater. If these do not exist, then no further special density testing is performed.

Bottom Line Results 2010







COST IMPACTS: A WSDOT Example

Washington State

US Highway 12 (MP 102 – 118)

Approximately 32 lane miles



Thermal segregation resulted in failure five years prior to anticipated 20 year life



ESTIMATED EXTRA COST: \$2.4 MILLION



Calculations:

•If this trend continues, over a 60 year period, an entire additional overlay will be needed

•Mill and Overlay of 1.8" on average cost of about \$200,000 per lane mile

• For this stretch of highway, thermal segregation risks a cost increase of:

•\$2.4 million in present dollars

- or -

•\$24.9 million in year 60 dollars



Without thermal segregation

With thermal segregation





NCAT (2000) and TTI (2002) similarly found thermal uniformity suitable for detecting segregation

• NCAT – low severity segregation/density when $\Delta t > 18$ °F

 TTI – when ∆t > 25 °F, TxDOT density uniformity requirements not met





HISTORY OF PAVE-IR

TxDOT funded research conducted by Texas Transportation Institute (TTI) to study the relationship between thermal segregation and density, in addition to developing a method for practical data collection.



Initial research included the use of a thermal camera operated by a researcher in the back of a pickup truck. In addition to obvious safety considerations, this initial method was found not to be practical. A series of infrared images had to be manually combined to produce a complete profile. Distance and position data were also difficult to incorporate.



First generation Pave-IR system was first used in October 2003.

HISTORY OF PAVE-IR

- Propelled manually
- Long setup time
- Loose connection wires
- Unstable wheel design
- Battery powered
- Required two operators





HISTORY OF PAVE-IR

Third generation Pave-IR system was first used in January 2005.

IMPROVEMENTS

- Paver mounted
- Rapid setup time
- Central master control
- No dedicated operator

CHALLENGES

- Battery powered
- Distance measuring wheel
- Components not suitable for everyday use on heavy equipment.





 In 2005 TTI published research reports outlining the relationship between thermal segregation and density.
 These reports also outline the methods used for thermal data collection supporting Pave-IR as the preferred tool for thermal data collection.

> Reports available online at: http://tti.tamu.edu/documents/0-4577-2.pdf http://tti.tamu.edu/documents/5-4577-01-1.pdf

• Following the completion of this research, TTI & TxDOT were interested in finding a commercial partner for development and production of Pave-IR systems for future implementation into TxDOT specifications.



MOBA PAVE-IR



MOBA PAVE-IR SYSTEM COMPONENTS

12 – Infrared sensors (standard)
Absolute encoder used for distance measurement
MOBA OPERAND[™] computer
GPS antenna
Includes PAVE PROJECT MANAGER[™] software for
post analysis and reports
Kit includes system cabling and all necessary screed
mounting hardware.



- Paver mounted system used to identify thermal segregation in newly placed asphalt surfaces.
- Uses a series of infrared, GPS, and distance measuring sensors.

WHAT IS PAVE-IR?

- Sensors are networked together and connected to a mobile computer with color display.
- Computer processes and displays data from all sensors.
- Areas where thermal segregation is present are displayed in real-time.
 - Data stored on flash drive for post processing on PC



PAVE-IR INSTALLATION





The MOBA Operand[™] compute attaches to sensor beam.

GPS antenna mounts above the Operand[™] computer.

Memory drive connects directly to Operand[™] computer

System is powered by machine voltage (10-28 VDC).

Sensor beam is hinged in center for easy setup and storage.



PAVE-IR INSTALLATION





The PAVE-IR[™] system mounts to the screed walkway by bolting or welding.



The distance encoder mounts to the wheel or torque hub using a magnet.



BENEFITS OF PAVE-IR

- **Provides full coverage of entire paved surface.**
- Ensures compliance with most existing DOT temperature specification requirements.
 - Data is logged automatically and can be stored permanently.
 - More cost effective versus infrared cameras. System also records paving speed and paver stops.
 - System can be moved from one machine to another.
 - System is scaleable from 2-8 meters depending on paving width

ONGOING DEVELOPMENT



Next Generation PAVE-IR(I)

- Real-time (pre-compacted) IRI smoothness measurement.
- Network (wireless) to onboard compaction systems.
- Wireless transmission of job data to QC office or plant.
- Grade and slope control monitoring.
- Material control (auger/conveyor) system monitoring.
- Infrared scanner mounted above paver deck.



Prototype Scanner













DATA COLLECTION SCREEN



MOBA PAVE-IR



FULL SCREEN MODE



MOBA PAVE-IR



Viewing									
Thermal Profile Results Summary									
Number of Profiles	Moderate]25°F;50°F]				Severe 3	Status			
54	Num	ber	Percent	r	Number	Percent			
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After data collection, the project file is transferred to PC via USB cable.

PPM allows contractor to evaluate the project in detail.

PPM displays thermal data, stations, paving speed, paver stops, and GPS location for any position in the project.

QC/QA reports are generated by PPM.



PROJECT PROPERTIES WINDOW (Meta Information)

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				Interpolation Linear
				Sample Spots of Interest Enabled
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			45.20442° N	Length 200.00ft
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Meta Information	Creation date	10/28/2009		
Metrics	File name	C:\Documents and Settings\jlano\Desktop\James Lano Files\TTI\Pave_2009102872510.log		
	Version	4.0		
	Project			
	Beginning location	north of stillwater		
	Comment	demo 1 E		
	Layer trickness	1		
	Measure height	Oft		
	Operator Name	paul		
	Paving width	12.5ft		
	Roadway ID	95 southbound		
	E Stations	749 (Ascending); 0.00ft; 100.00ft;		
	Interval	100ft		
	Order	Ascending		
	Project offset	Oft		
	System			
	Data Collect Beginning	8:06 AM		
	Noting radius	14.002m 12in		
	Sensor space	1.083ft		
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			Save	
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PROJECT PROPERTIES WINDOW (Metrics)

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Meta Information	Project Duration: 9:58:43 htmts							
Metrics	Paver Total Stop Time: 4:50:53 h:m:s							
	Paver Average Speed: 27.26 ft/min							
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TIME DIAGRAM DISPLAYS PAVER STOPS





SPEED DIAGRAM DISPLAYS PAVING SPEED





TEMPERATURE DIAGRAM DISPLAYS TEMPERATURE GRAPH





PPM QC/QA REPORT GENERATION

Tex-244-F Part II

Thermal Profile Summary Report

Profile ID:	SH-114	Profile Date:	11/16/2009 7:38:53 PM
Profile Number:	1	Letting Date:	10/5/2009
Status:		Controlling CSJ:	
County:	Dallas	Spec Year:	2009
Tested By:	J. Lano (MOBA)	Spec Item:	
Test Location:	WALNUT HILL LN	Special Provision:	341-024
Material Code:	FC12	Mix Type:	
Material Name:		a dati kan a sa an da	an a
Producer:	ABR		
Area Engeneer:		Project Manager:	

Course/Lift:	2	Temperature Differential Threshold:	25.0	
Segment Length (ft):	150	Sensors Ignored:	-	

Thermal Profile Results Summary							
Number of Profiles	Mod 25.0°F < differe	erate ential <= 50.0°F	Severe differential > 50.0°F				
55	Number	Percent	Number	Percent			
55	6	11	10	18			

ID: SH-114

Page: 1

Reports specific to various DOT specifications can be generated in PPM.

This report is based on TxDOT thermal specification Tex-244-F



TEX-244-F REPORT

Summary of Locations with Thermal Segregation									
Drofile	Begir	nning Location	Enc	ling Location	Mov	Min	Townseture		
Nr	Distance (ft)	GPS in °	Distance (ft)	GPS in °	Temp	Temp	Differential		
2	150.50	96.95501 W, 32.88593 N	300.00	96.95462 W, 32.88572 N	309.9	283.8	26.1		
20	2850.07	96.94865 W, 32.88120 N	2999.58	96.94837 W, 32.88087 N	316.8	257.9	58.9		
21	3000.08	96.94837 W, 32.88087 N	3149.58	96.94813 W, 32.88054 N	311.2	248.9	62.3		
23	3300.09	96.94787 W, 32.88020 N	3449.56	96.94762 W, 32.87986 N	327.2	297.3	29.9		
31	4500.17	96.94655 W, 32.87720 N	4649.61	96.94649 W, 32.87680 N	324.1	296.6	27.5		
33	4800.06	96.94645 W, 32.87639 N	4949.50	96.94642 W, 32.87600 N	310.1	284.5	25.6		
36	5250.39	96.9464 W, 32.87519 N	5399.84	96.94639 W, 32.87480 N	318.9	291.4	27.5		
47	6900.28	96.94559 W, 32.87085 N	7049.73	96.94546 W, 32.87045 N	336.7	307.0	29.7		
48	7050.23	96.94546 W, 32.87045 N	7199.67	96.9452 W, 32.87014 N	351.7	294.1	57.6		
49	7200.17	96.9452 W, 32.87014 N	7349.62	96.94497 W, 32.86979 N	351.0	284.7	66.2		
50	7350.12	96.94497 W, 32.86979 N	7499.56	96.94474 W, 32.86944 N	349.7	264.4	85.3		
51	7500.06	96.94474 W, 32.86943 N	7649.50	96.94451 W, 32.86909 N	348.8	268.3	80.5		
52	7650.00	96.94451 W, 32.86909 N	7799.95	96.94425 W, 32.86876 N	349.7	257.9	91.8		
53	7800.45	96.94425 W, 32.86876 N	7949.89	96.94399 W, 32.86842 N	352.0	247.3	104.8		
54	7950.39	96.94399 W, 32.86842 N	8099.84	96.9437 W, 32.86809 N	348.4	262.9	85.5		

Summary of Locations with Thermal Segregation

Profile Nr	Beginning Location		Ending Location		Max	Min	Temperature
	Distance (ft)	GPS in °	Distance (ft)	GPS in °	Temp	Temp	Differential
55	8100.34	96.9437 W, 32.86809 N	8214.80	96.94349 W, 32.86786 N	328.8	243.9	85.0

Summary of Locations Without Thermal Segregation

Drofile	Begir	nning Location	Enc	ling Location	Max	Min	Tomporaturo	
Nr	Distance (ft)	GPS in °	Distance (ft)	GPS in °	Temp	Temp	Differential	
1	0.00	96.95544 W, 32.88615 N	150.00	96.95501 W, 32.88593 N	295.9	275.5	20.3	
3	300.50	96.95462 W, 32.88572 N	450.00	96.95423 W, 32.88550 N	311.9	288.1	23.8	
4	450.50	96.95422 W, 32.88550 N	599.50	96.95384 W, 32.88529 N	318.4	305.1	13.3	
5	600.00	96.95383 W, 32.88529 N	749.51	96.95344 W, 32.88507 N	319.6	305.2	14.4	
6	750.01	96.95344 W, 32.88507 N	899.51	96.95303 W, 32.88485 N	317.3	303.3	14.0	
7	900.01	96.95303 W, 32.88485 N	1049.52	96.95262 W, 32.88462 N	313.0	290.1	22.9	
8	1050.02	96.95262 W, 32.88462 N	1199.52	96.95223 W, 32.88441 N	300.9	283.5	17.5	
9	1200.02	96.95222 W, 32.88441 N	1349.53	96.95182 W, 32.88418 N	303.1	285.6	17.5	
10	1350.03	96.95182 W, 32.88418 N	1499.53	96.95145 W, 32.88394 N	305.1	291.7	13.3	
11	1500.03	96.95145 W, 32.88393 N	1649.54	96.95109 W, 32.88368 N	308.3	294.6	13.7	
					-			

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- Specified in Texas, Ohio, Louisiana, Minnesota, Washington
- SHRP 2 Study completed(Recommend Implementation)
- SHRP 2 Research extension of 18 month to help states implement
- EveryDayCounts/IC

NCAT Alabama Study
 AASHTO Spec Draft





Thank You!

Questions?

MOBILE AUTOMATION

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